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Feedback Control of Multiple Hemodynamic Variables with Multiple Cardiovascular Drugs

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Abstract— **The ultimate goal of disease treatment is to control the biological system beyond the native regulation to combat pathological process. To maximize the advantage of drugs, we attempted to pharmacologically control the biological system at will, e.g., control multiple hemodynamic variables with multiple cardiovascular drugs. A comprehensive physiological cardiovascular model enabled us to evaluate cardiovascular properties (pump function, vascular resistance, and blood volume) and the feedback control of these properties. In 12 dogs, with dobutamine (5±3 μg·kg^{-1}·min^{-1}), nitroprusside (4±2 μg·kg^{-1}·min^{-1}), dextran (2±2 ml·kg^{-1}), and furosemide (10 mg in one, 20 mg in one), rapid, sufficient and stable control of pump function, vascular resistance and blood volume resulted in similarly quick and stable control of blood pressure, cardiac output and left atrial pressure in 5±7, 7±5, and 12±10 minutes, respectively. These variables remained stable for 60 minutes (RMS 4±3 mmHg, 5±2 ml·min^{-1}·kg^{-1}, 0.8±0.6 mmHg, respectively).**

I. Introduction

THE ultimate goal of disease treatment is to control the biological system beyond the native regulation to combat pathological process. This control may be partly achieved by native regulatory systems, but these frequently fail when disease progresses.

Many pharmacological treatments have provided us with control measures that may act in ways not possible by native regulators. To fully take advantage of these medicines, we must establish ways of using these agents to control the biological system at our will. As an example, we tried to control multiple hemodynamic variables with multiple cardiovascular drugs.

Several closed-loop systems have succeeded in directly controlling a single hemodynamic variable [1,2]. Multiple-variable control, however, has been unsuccessful [3-5].

Multiple-input multiple-output feedback control remains a challenge if the input-output relationships for all combinations are of equal significance. We therefore tried to decouple the input-output relationships by using a comprehensive physiological cardiovascular model. The model enabled us to define a set of parallel independent relationships between cardiovascular properties and drugs: pump function / inotrope, vascular resistance / vasodilator, and blood volume / volume expander. The model also provided us with a method to quantitatively calculate cardiovascular properties.

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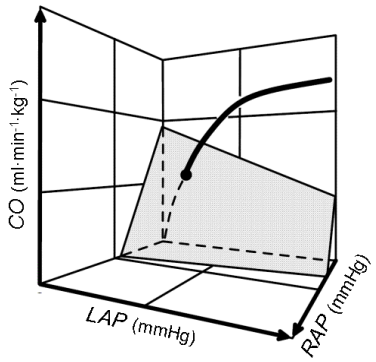

Fig. 1. Extended Guyton's model.
Thick curve, pump function of left and right heart; shaded surface, capacitive function of total vascular beds; CO, cardiac output; LAP, left atrial pressure; RAP, right atrial pressure.

II. Model and Methods

A. Cardiovascular property identification

Abnormalities of hemodynamic variables arise from abnormalities of cardiovascular properties, including pump function, vascular resistance, and blood volume. We identified these properties using an extended version of Guyton's circulatory equilibrium framework (Fig. 1) [6,7].

Pump function of the left heart (S_L) can be quantified as the ratio of cardiac output (CO) to the logarithm of left atrial pressure (LAP) ($S_L = CO / [\ln (LAP - 2.03) + 0.80]$). Systemic vascular resistance (R) can be calculated as blood pressure (BP) minus right atrial pressure (RAP) divided by CO. Stressed total blood volume (V) is obtained by $V = (CO + 19.61\ RAP + 3.49\ LAP) \times 0.129$.

B. Autopilot System

Autopilot controller of multiple hemodynamic variables consisted of multiple feedback loops. We designed these

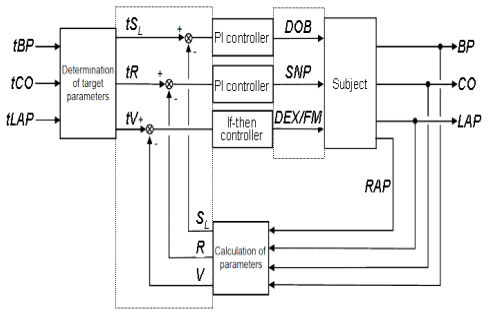

Fig. 2. Autopilot controller.
Calculated cardiovascular properties, rather than hemodynamic variables, were feedback-controlled to achieve multiple independent control of variables.

feedbacks as being independent of each other. The selection and the combination of controlled property and the controlling drugs enabled the independent operation (Fig. 2) [8].

S_L and R were controlled by proportional-integral (PI) feedback, with infusion of dobutamine (DOB) and sodium nitroprusside (SNP), respectively. Proportional and integral gain values were calculated using Chien-Hrones-Reswick's method [9] from gain, time constant, and dead-time delay of the approximated first-order step responses of S_L to DOB and R to SNP. We infused 10% dextran 40 solution (DEX, 10 ml·min^{-1}) as long as V was <1 ml·kg^{-1} than the target, and injected furosemide (FM, 10 mg) every 20 minutes while V was >2 ml·kg^{-1} than the target.

C. Animal Experiments

We evaluated the performance of the autopilot controller in 12 adult anesthetized mongrel dogs (both sexes, 25±4 kg). We measured BP, CO, LAP and RAP. DOB, SNP, and DEX were automatically administered into the femoral vein through independent infusion routes, using either a computer-controlled roller pump or an infusion pump. FM was given through the jugular vein manually according to computer instructions.

These dogs underwent coronary microembolization, resulting in left ventricular failure. After hemodynamic stabilization, we began implementing control using the autopilot system.

III. Results

	Proportional gain (K_p) μg·ml^{-1}	Integral gain (K_i) sec^{-1}
S_L control	0.06	0.01
R control	-1.37	0.007

Table 1. Selected gain parameters for designed controller.
Dose (μg·kg^{-1}·min^{-1}) of drugs for the control of S_L (DOB) or R (SNP) is determined as (Dose) = K_p (1 + K_i / s) Δ(Controlled variable)

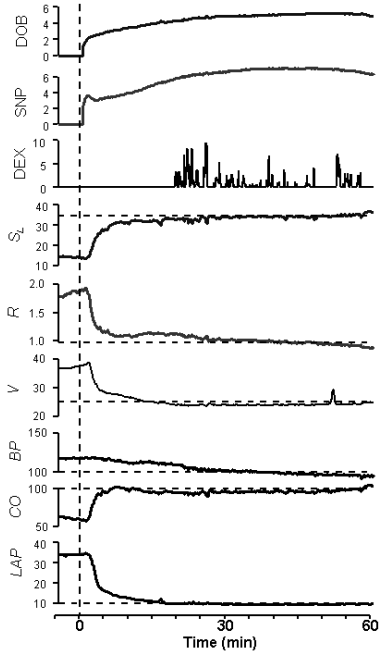

Fig. 3. An example of the automatic control of hemodynamics.
Feedback control was rapid, sufficient, and stable. DOB, dobutamine (μg·kg^{-1}·min^{-1}); SNP, sodium nitroprusside (μg·kg^{-1}·min^{-1}); DEX, dextran 40 solution (ml·min^{-1}); S_L, pump function (ml·kg^{-1}·min^{-1}); R, resistance (mmHg·ml^{-1}·kg·min); V, blood volume (ml·kg^{-1}); BP, blood pressure (mmHg); CO, cardiac output (ml·kg^{-1}·min^{-1}); LAP, left atrial pressure (mmHg)

Based on the step response from coronary microembolized dogs, we determined the proportional and integral gain as shown in Table 1.

Similar to the example shown in Figure 3, in 12 dogs, by administering DOB (5±3 μg·kg^{-1}·min^{-1}), SNP (4±2 μg·kg^{-1}·min^{-1}), DEX (2±2 ml·kg^{-1}), and FM (10 mg in one, 20 mg in one), rapid, sufficient and stable control of S_L, R and V. This resulted in corresponding appropriate control of BP, CO and LAP in 5±7, 7±5, and 12±10 minutes, respectively. These remained stable for 60 minutes (RMS BP=4±3 mmHg, CO=5±2 ml·min^{-1}·kg^{-1}, LAP=0.8±0.6 mmHg).

IV. Discussion

We have shown that by evaluating cardiovascular properties (pump function, vascular resistance, and blood volume), and then controlling these properties with individually selected drugs, we were able to automatically control multiple hemodynamic abnormalities rapidly, stably, and simultaneously.

Direct control of multiple hemodynamic variables, however, likely fails because each drug affects more than one variable. Direct control remains unfeasible even with more complicated methods developed in control engineering; appropriate physiological modeling and precise evaluation of cardiovascular properties are essential to achieving adequate control.

V. Conclusion

Calculating cardiovascular properties (pump function, vascular resistance, and blood volume) based on a comprehensive cardiovascular model and feedback control of these properties are required for the accurate control of multiple hemodynamic variables (BP, CO, LAP).

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