

A Comparison of Color Correction Algorithms for Endoscopic Cameras

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Abstract—Quantitative color tissue analysis in endoscopy examinations requires color standardization procedures to be applied, so as to enable compatibility among computer aided diagnosis application from different endoscopy labs. The objective of this study was to examine the usefulness of different color correction algorithms (thus facilitating color standardization), evaluated on four different endoscopy cameras. The following five color correction algorithms were investigated: two gamma correction based algorithms (the classical and a modified one), and three (2nd, 3rd, and 4th order) polynomial based correction algorithms. The above algorithms were applied to four different endoscopy cameras: (a) Circon, (b) Karl-Storz, (c) Olympus, and (d) Snowden-Pencer. The color correction algorithms and the endoscopic cameras evaluation, was carried out using the testing color palette (24 colors of known digital values) provided by the Edmund Industrial Optics Company. In summary, we have that: (a) the modified gamma correction algorithm gave significantly smaller mean square error compared to the other four algorithms, and (b) the smallest mean square error was obtained for the Circon camera. Future work will focus on evaluating the proposed color correction algorithm in different endoscopy clinics and compare their tissue characterization results.

I. INTRODUCTION

In recent years, endoscopy, colonoscopy, gatroendoscopy, and laryngoscopy examinations use medical cameras to monitor human organs with minimum complications. These methods are the most popular ones, compared with classical open surgery procedures which are used in special conditions due to the complications that are associated with [1]-[4].

Quantitative color tissue analysis in endoscopy examinations requires color standardization procedures to be applied; enabling computer aided diagnosis, as well as monitoring the sensitivity and specificity performance of different endoscopy labs. The objective of this study was to examine the usefulness of different color correction algorithms (thus facilitating color standardization), evaluated on four different endoscopy cameras.

These will support the physician opinion and will help her/him to increase the accuracy of the diagnosis providing

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better quality videos/images.

It was demonstrated by our group that gamma color correction is a necessary pre-processing component for the development of a Computer Aided Diagnostic (CAD) system able to differentiate between normal and abnormal endometrial tissue in the early stages of gynaecological cancer based on color texture analysis in hysteroscopy imaging [5]-[7]. The need of standardization efforts for reporting endoscopy examinations including color standardization were proposed in [8]. Moreover, the usefulness of gamma color correction was clearly demonstrated in microscopy imaging as well [9].

Additional algorithms for color standardization include the use of polynomial correction fitting, recently used for regular cameras as well [10].

The structure of this paper is as follows. Section II presents the methodology. Section III the results, and Section IV the concluding remarks.

II. METHODOLOGY

A. Recording of Endoscopic Video

The following endoscopy cameras were used: Circon [11], Karl-Storz [12], Olympus [13], and Snowden-Pencer [14].

B. Recording of Testing Targets

The testing color palette provided by Edmund Industrial Optics Company [15], with known color distribution was used in this set of experiments (see Figure 1, and Table I). The general purpose of a test pattern is to determine the true color balance or optical density of any color system. It is an industry standard that provides a non-subjective comparison with a test pattern of 24 carefully prepared colored squares (see Figure 1). Each square in the pattern represents a natural color like the human skin, foliage, blue sky, etc.

Testing images were captured in the surgery room with natural daylight illumination (D65) and focusing based on the experience of the physician, using the four cameras under investigation. Following the above procedure, we captured and saved the video (AVI format) of the testing palette using the VCE-PRO frame grabber [16], (24 bits color at 25 frames per second) and then extracted uncompressed TIFF images of the 24 color squares, 64X64 pixels. The corresponding targets were digitally generated based on the data given by the Edmund Optics Company [15], as the ground truth of the experiment (see Figure 1). RGB values for some of the testing targets provided by the manufacturer are given in Table I.

C. Color correction algorithms

1) *Classical Gamma Correction*: The classical gamma correction algorithm based on the following equations was used in [17]:

$$\begin{aligned} R_{out} &= \alpha_R R_{in}^{\gamma_R} + b_R \\ G_{out} &= \alpha_G G_{in}^{\gamma_G} + b_G \\ B_{out} &= \alpha_B B_{in}^{\gamma_B} + b_B. \end{aligned} \quad (1)$$

The R_{in} , G_{in} and B_{in} denote the original Red, Green and Blue color signals and R_{out} , G_{out} and B_{out} denote the corrected output color signals. The computation of the parameters was based on the non-linear least squares algorithm (see `lsqnonlin` function in MATLAB [18]). We estimate the gamma and offset values in each channel, R , G , B and b_R , b_G , b_B respectively (see eq. 1).

TABLE I
R, G, AND B VALUES OF COLOR PALLET FROM THE EDMUND INDUSTRIAL OPTICS COMPANY

Color	R	G	B
Black	0	0	0
White	255	255	255
Red	203	0	0
Green	64	173	38
Blue	0	0	142
Dark skin	94	28	13
Light skin	241	149	108
Blue sky	97	119	171
Foliage	90	103	39
Blue flower	164	131	196
Orange	255	116	21
Magenta	207	3	124



Fig. 1. The testing targets of the color palette with known color distribution from the Edmund Industrial Optics Company [15]

2) *Gamma Correction algorithm*: This model is based on the following equations:

$$\begin{bmatrix} R_{out'} \\ G_{out'} \\ B_{out'} \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} R_{in} \\ G_{in} \\ B_{in} \end{bmatrix} + \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} =$$

$$= A \begin{bmatrix} R_{in} \\ G_{in} \\ B_{in} \end{bmatrix} + k \quad (2)$$

$$\begin{aligned} R_{out} &= 255(R_{out'}/255)^{\gamma_R} \\ G_{out} &= 255(G_{out'}/255)^{\gamma_G} \\ B_{out} &= 255(B_{out'}/255)^{\gamma_B}. \end{aligned} \quad (3)$$

The $[R_{out'} \ G_{out'} \ B_{out'}]^T$ denote the original input Red, Green, and Blue components of the target image (see eq. 2, 3). The $[R_{out} \ G_{out} \ B_{out}]^T$ denote the output (corrected) RGB components of the target image. The output signal was multiplied, using a linear matrix A and a constant offset matrix k . The non-linear gamma model can be approached using (3). The computation of the parameters was based on the non-linear least squares algorithm (see `lsqnonlin` function in MATLAB [18]). We estimate matrices A , k and the gamma values in each channel, R , G , B and the result is the correction of the output signal.

3) *Polynomial 2nd, 3rd, and 4th order Correction*: The polynomial 2nd, 3rd, and 4th order correction algorithms were based on the following equation (given for the case of 4th order) [10]:

$$\begin{aligned} R_{out} &= \alpha_{R_0} + \alpha_{R_1} R_{in} + \alpha_{R_2} R_{in}^2 + \alpha_{R_3} R_{in}^3 + \alpha_{R_4} R_{in}^4 \\ G_{out} &= \alpha_{G_0} + \alpha_{G_1} G_{in} + \alpha_{G_2} G_{in}^2 + \alpha_{G_3} G_{in}^3 + \alpha_{G_4} G_{in}^4 \\ B_{out} &= \alpha_{B_0} + \alpha_{B_1} B_{in} + \alpha_{B_2} B_{in}^2 + \alpha_{B_3} B_{in}^3 + \alpha_{B_4} B_{in}^4 \end{aligned}$$

The R_{in} , G_{in} and B_{in} denote the original Red, Green and Blue color signals and R_{out} , G_{out} and B_{out} denote the corrected output color signals. The computation of the terms for each channel was based on the non-linear least squares algorithm (see `lsqnonlin` function in MATLAB [18]).

D. Parameter Estimation Using Cross Validation

Two different experiments were carried out. In experiment 1 only one set of testing target videos were recorded for the 4 different endoscopic cameras. No cross validation was carried out, and the color correction was applied on the same set of images the correction parameters were derived.

In experiment 2, 5 different sets of color targets were extracted from the captured videos, and five different runs of the color correction algorithms were carried out using the leave one out method. Thus in each run, the training (i.e. extracting of the color correction parameters) was carried out on the 4 set of targets, and the evaluation (i.e. application of the color correction parameters) on the remaining one.

III. RESULTS

A. Experiment I

Table II tabulates the mean square error (MSE) for 5 color correction algorithms for the 4 cameras under study. The gamma correction algorithm gave the smallest MSE values. The Circon camera gave also the smallest MSE values, followed by the Karl-Stortz camera.

TABLE II
MEAN SQUARE ERROR FOR EACH COLOR CORRECTION ALGORITHM FOR 4 DIFFERENT ENDOSCOPIC CAMERAS (SEE III.A EXPERIMENT 1)

COLOR CORRECTION ALGORITHM	Circon				Karl-Storz				Olympus				Snowden-Pencer			
	R	G	B	Σ RGB	R	G	B	Σ RGB	R	G	B	Σ RGB	R	G	B	Σ RGB
Classical Correction	456	57	320	833	671	110	505	1286	525	32	439	996	1427	166	1259	2852
Gamma Correction	40	58	93	191	110	62	35	207	203	31	62	296	250	135	839	1224
Polynomial 2nd order	424	61	317	802	647	100	493	1240	523	32	439	994	1425	166	1260	2851
Polynomial 3rd order	416	53	314	783	605	100	467	1172	468	31	393	892	1421	165	1251	2837
Polynomial 4th order	402	48	290	740	1109	92	477	1678	475	32	390	897	1421	159	1251	2831

R, G, B represent the MSE for the Red, Green, and Blue channels respectively, whereas Σ RGB represents their sum.

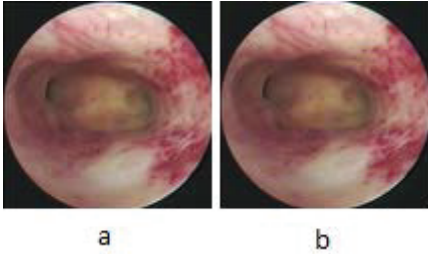


Fig. 2. Endometrium images (a) before and (b) after gamma correction algorithm.

B. Experiment II

Table III tabulates the results of the mean of the MSE for 5 runs for the 5 color correction algorithms. The mean of the MSE for the 5 runs for the evaluation set was computed for each color correction algorithm for each channel. In this experiment, only the Circon endoscopic camera was used (i.e. the one that gave the smallest MSE in Experiment 1). Again, the gamma correction algorithm gave the smallest MSE values. An Example of the Application of Color Correction on Hysteroscopy Imaging Figure 2 gives an example of an uncorrected and the corresponding corrected hysteroscopy images of the endometrium. It is shown that the corrected image is brighter, and based on physician opinion it is of better quality, and can support her/his diagnosis easier.

TABLE III
MEAN SQUARE ERROR FOR EACH COLOR CORRECTION ALGORITHM FOR THE CIRCON ENDOSCOPIC CAMERA (SEE III.B EXPERIMENT 2)

COLOR CORRECTION ALGORITHM	Circon			
	R	G	B	Σ RGB
Classical Correction	444	375	940	1759
Gamma Correction	147	73	181	401
Polynomial 2nd order	449	76	542	1067
Polynomial 3rd order	394	76	510	980
Polynomial 4th order	551	868	518	1937

IV. CONCLUDING REMARKS

Quantitative color tissue analysis in endoscopy examinations requires color standardization procedures to be applied,

enabling computer aided. The objective of this study was to examine the usefulness of different color correction algorithms (thus facilitating color standardization), evaluated on four different endoscopy cameras. The following five color correction algorithms were investigated: two gamma correction based algorithms (the classical and a modified one), and three (2nd, 3rd, and 4th order) polynomial based correction algorithms. These algorithms were applied on four different endoscopy cameras: (a) Circon, (b) Karl-Storz, (c) Olympus, and (d) Snowden-Pencer. The color correction algorithms and the endoscopic cameras evaluation, was carried out using the testing color palette (24 colors of known digital values) provided by the Edmund Industrial Optics Company. It was shown that: (a) the modified gamma correction algorithm gave significantly smaller mean square error compared to the other four algorithms, and (b) the smallest mean square error was obtained for the Circon camera. Thus, the color correction algorithm can be used to standardize endoscopy images, given that to the best of our knowledge, there are no guidelines for the color calibration of the endoscopy cameras [19]-[24].

Furthermore, these findings were applied to hysteroscopy imaging for differentiating between normal and abnormal tissue of the endometrium with very promising results. More specifically, the Circon endoscopy camera was used, and the gamma color correction algorithm. Texture analysis on the manually segmented regions of interest (ROIs) demonstrated that normal ROIs have higher gray level, and lower variance and contrast when compared to abnormal ROIs [5]. Homogeneity was slightly lower, and entropy slightly higher of the abnormal ROIs when compared to the normal ones.

Future work will focus on evaluating the proposed color correction algorithm in different endoscopy clinics using different equipment and compare their tissue characterization results. Furthermore, we hope that the proposed methodology can also be applied to other endoscopic modalities such as colonoscopy and gastro endoscopy.

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